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Organizer:  **TESTING
SOLUTIONS
& SERVICES**

Testing Solution for VR apps

Presented by Carlos Cárdenas (DEKRA)

Motivation Facts

- Mobile applications consume data differently depending on various network conditions.
- Carriers need to understand how the most popular Android and iOS apps consume data from the network.
- Carriers need to understand the network conditions that drive poor/excellent User Experiences.
- Carriers need to test an app in the exact same manner that customer use apps. No simulations...just real apps consuming real data.

DEKRA's current solution for non VR apps

- Non VR Apps:
 - Downlink Intensive Video Streaming (including 4k)
 - Uplink Intensive Video Streaming
 - Two-way Video Streaming
 - Social Media



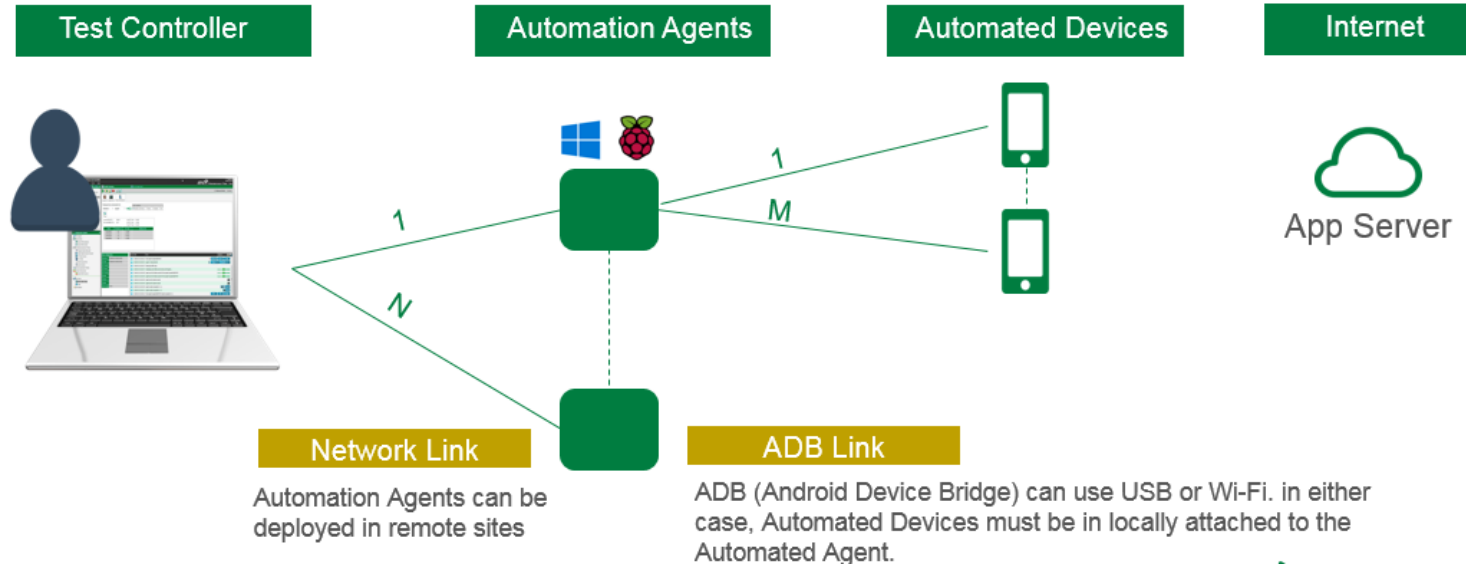
Instagram



DEKRA's current solution for non VR apps

Testing Topology:

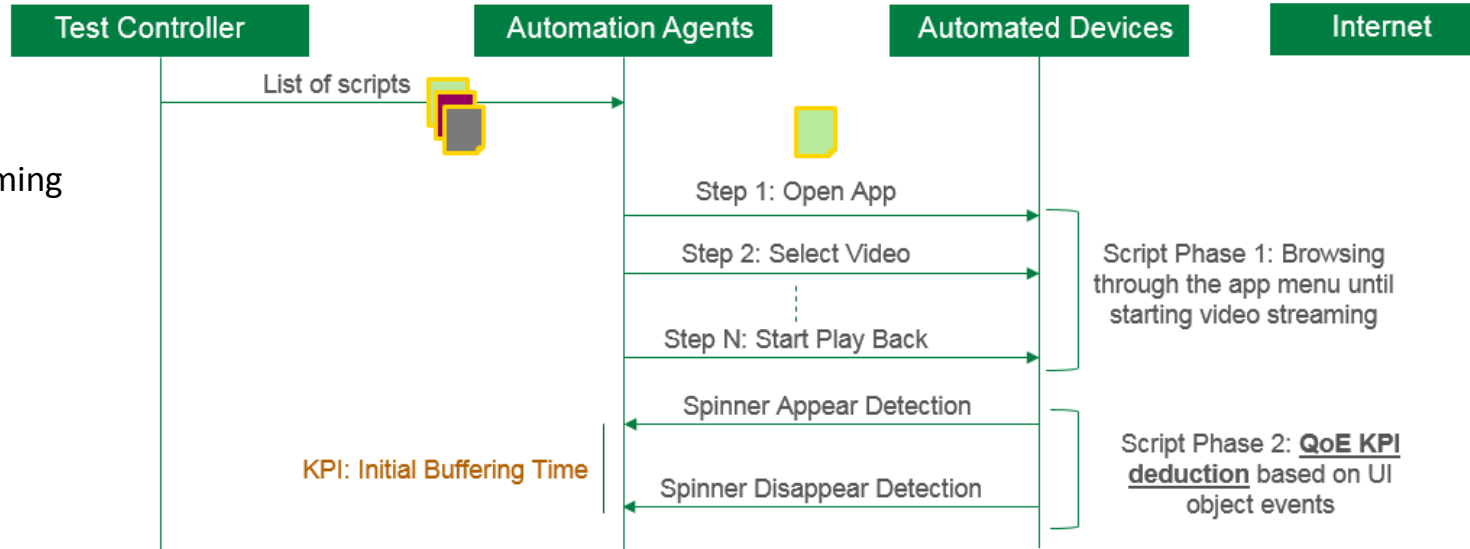
High Scalability: $M \times N$
devices can be
automated
simultaneously



DEKRA's current solution for non VR apps

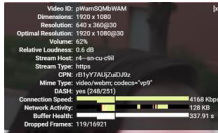
Automation Test Flow:

Example – Video Streaming
App



DEKRA's current solution for non VR apps

- **Appium** [open source test automation framework for use with native, hybrid and mobile web apps] for
 - Browsing through the App menu
 - Recognizing UI objects (e.g., spinner, progression bar)
- **ADB** (Android Device Bridge) for device data consumption reporting.
- **OCR** (Optical Character Recognition) for extracting App information:



Video Resolution
Buffer Health

DEKRA's current solution for non VR apps

The following KPIs have been proved:

Mobile Apps	KPIs
All (App Agnostic)	Battery, Data Usage, Throughput
Netflix	Initial Buffering, Re-bufferings
YouTube	Initial Buffering, Re-bufferings, Video Resolution
Instagram	Access Time, Initial Buffering, Re-bufferings
Periscope	Initial Buffering, Re-bufferings
Skype Video Call	Call Setup Time, Call Result, MOS
WhatsApp	Sharing Time, MOS
...	

DEKRA's current solution for non VR apps

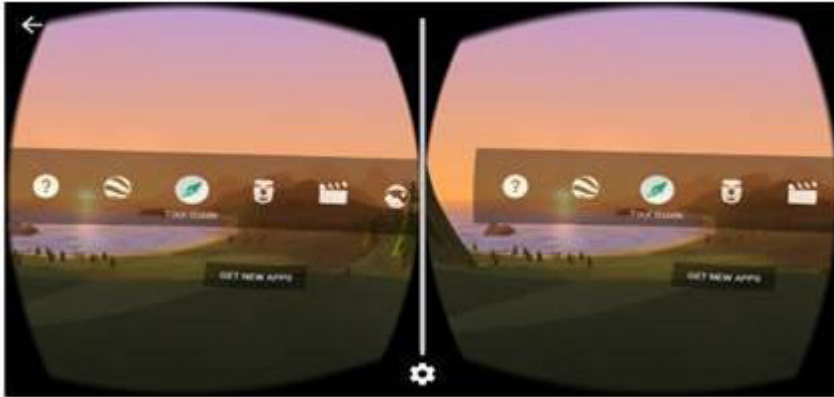
- **Limitations** of this approach for testing VR/Gaming apps:
 - Performing Movement
 - VR and gaming apps require physical movement of the hosting device. As the **gyroscope and accelerometer cannot be mocked**, a hardware platform is required.
 - Retrieving App state:
 - Unlike other apps, VR and gaming apps are programmed in an Android UI Canvas where the graphical engine works (e.g., Open GL). **Appium (or similar) cannot recognize UI objects inside the App gfx canvas.**



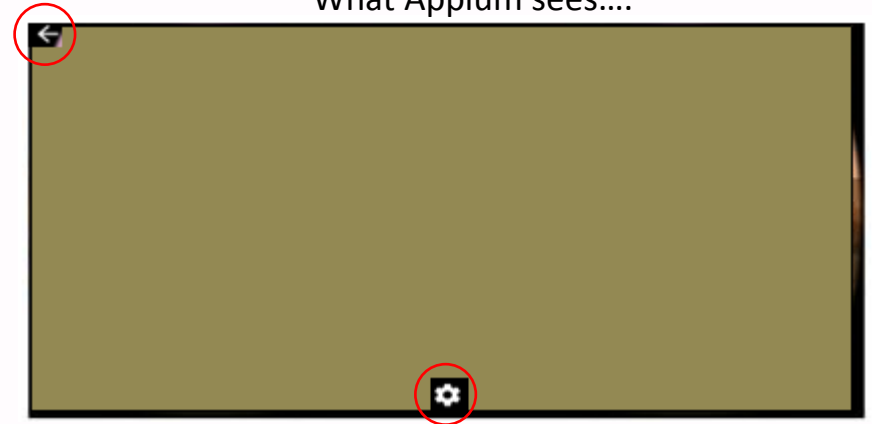
DEKRA's current solution for non VR apps

- **Limitations** of this approach for testing VR/Gaming apps:

Actual App UI

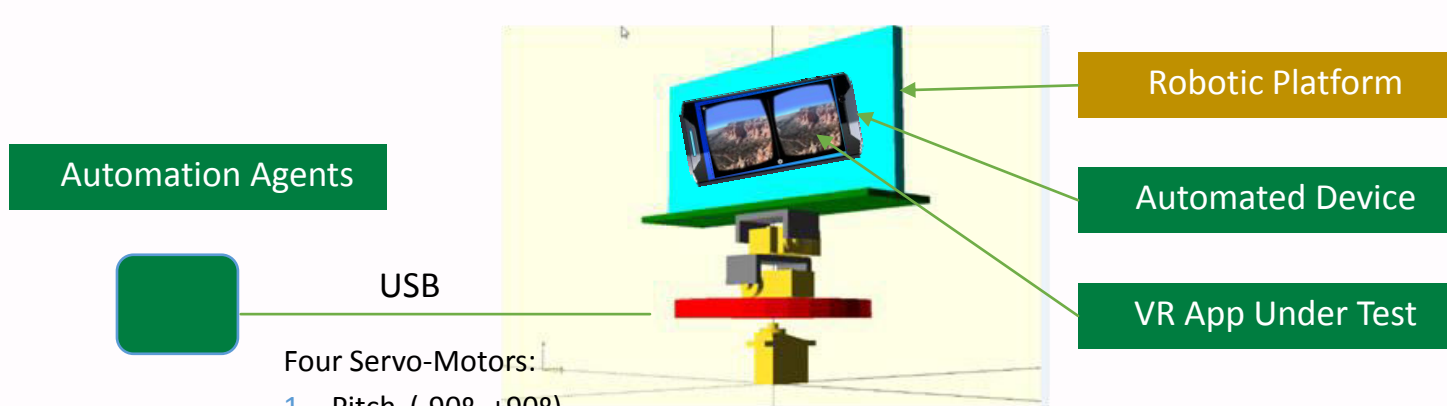


What Appium sees....



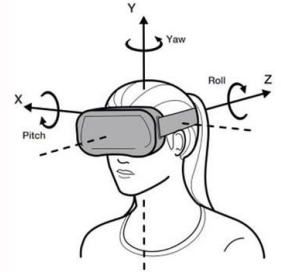
Testing solution for VR/Gaming apps

- In order to overcome those limitations we have upgrade the architecture:



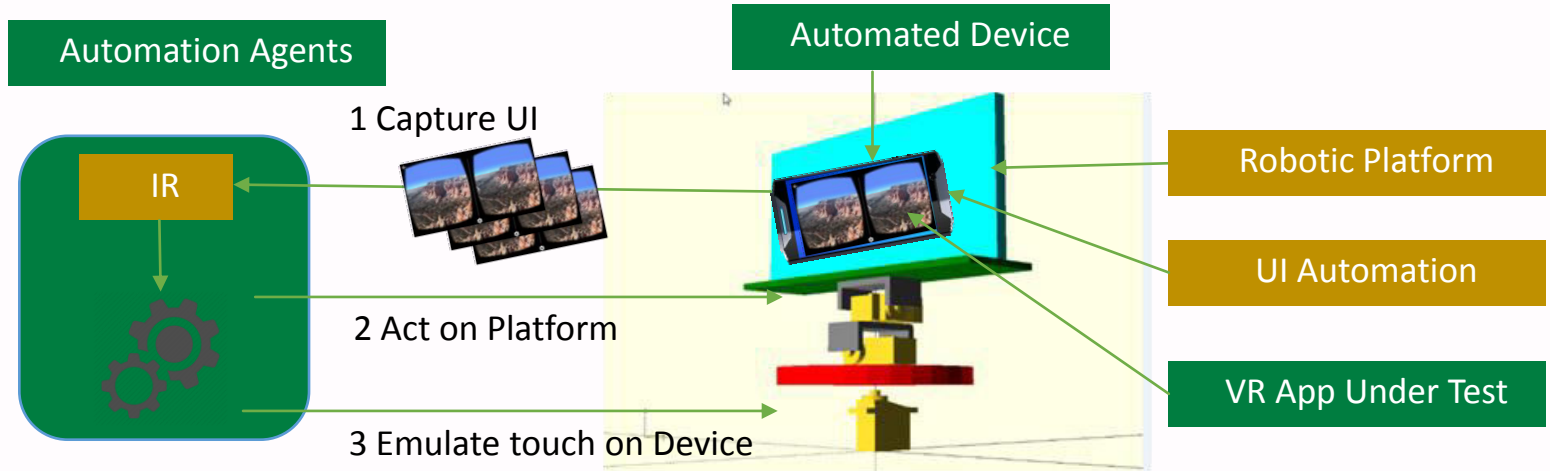
Four Servo-Motors:

1. Pitch (-90° , $+90^\circ$)
2. Yaw 1 (-180° , 0°)
3. Yaw 2 (0° , $+180^\circ$)
4. Roll (-90° , $+90^\circ$)



Testing solution for VR/Gaming apps

Architecture



Test Solution Requirements

Key Performance Indicators

- “Time to load a virtual scene” ($t_2 - t_1$), where
 - t_1 = user clicks on “start scene/experience” button
 - t_2 = the scene is totally rendered
- “Lagging” ($t_4 - t_3$), where
 - t_3 = user sends command to the app (e.g., roll phone)
 - t_4 = device UI shows command response (e.g., airplane has rolled)
- “Frame per seconds” as smoothness indicator...
- “Data Consumption”

Test Solution Requirements

Performance Requirements

- Minimize “reaction time” $t_5 - t_6$, where
 - t_5 = target appears on the screen
 - t_6 = tap/touch on that target

Why?

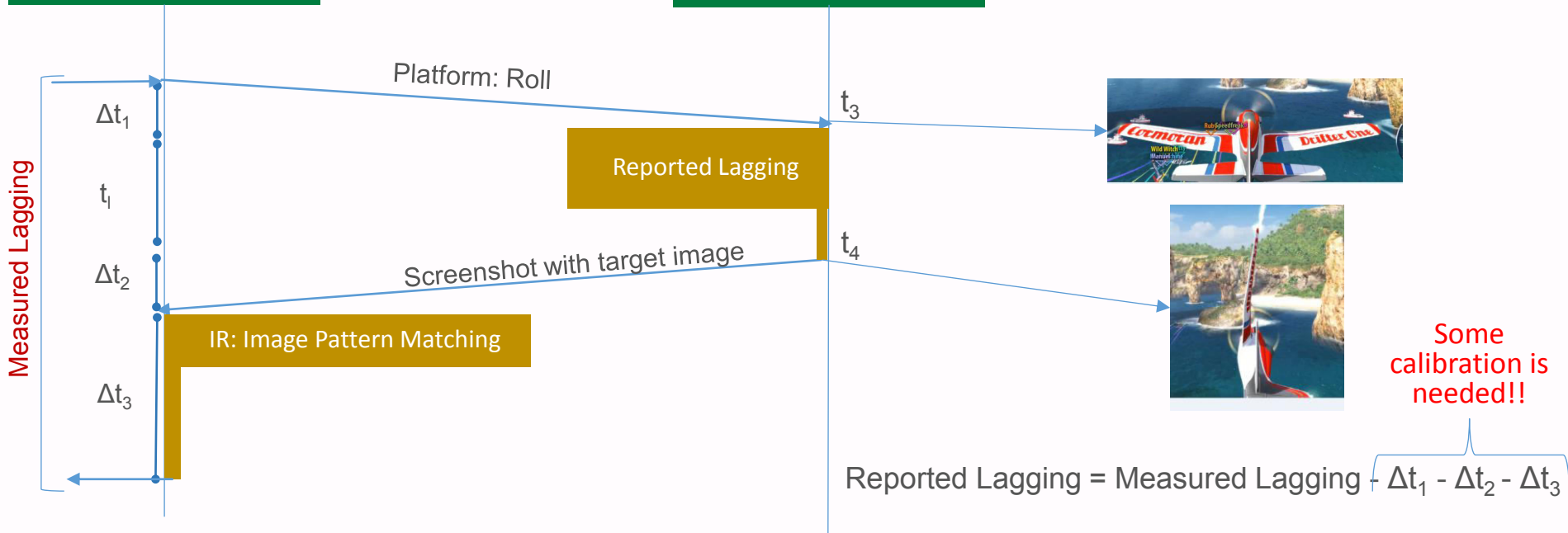
VR/Gaming: Automate the browsing through the app where some UI could be moving objects.

Gaming: Shoot at moving target

Automation Agents

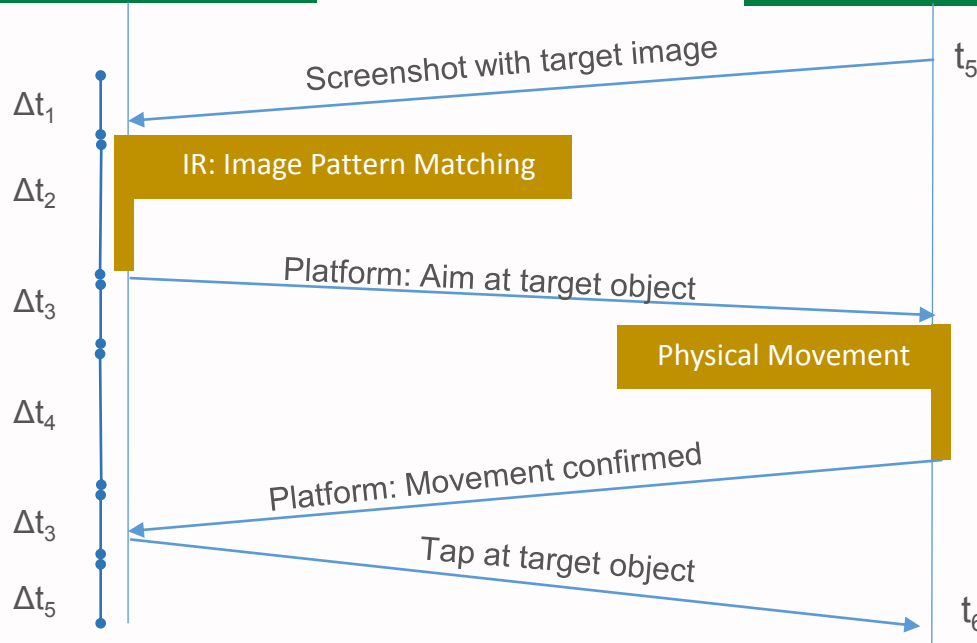
Automated Device / Robotic Platform

Measuring Lagging



Automation Agents

Automated Device / Robotic Platform



More on Reaction Time....

Goal

Average Human Reaction Time: **284 ms**

[<https://www.humanbenchmark.com/tests/reactiontime/statistics>]

Implemented Reaction Time:

$\Delta t_1 \sim 1-10$ ms \rightarrow TCP socket latency

$\Delta t_2 \sim 100-200$ ms \rightarrow Image Recognition performance

$\Delta t_3 \sim 1-10$ ms \rightarrow Serial Comm latency

$\Delta t_4 \sim 100$ ms \rightarrow Time to aim at object (Robotic action)

$\Delta t_5 \sim 1-10$ ms \rightarrow TCP socket latency

DEKRA's solution Reaction Time = **(230, 330) ms**

Test Solution Requirements

Performance Requirements

- High performance screen capture
 - Requirement: Higher than 24 frames per second
- Low delay screen touch
 - Requirement: Lower than 10 ms
- IR (Image Recognition)
 - Requirement: High pattern matching accuracy and high performance

Design Parameters

Options	Trade off	
Higher screenshot resolution	Higher Δt_1 and Δt_2	Less measurements, more accurate KPI, slow for gaming apps
	Less false negative IR detections	
	Less true IR positive detections	
Lower screenshot resolution	Lower Δt_1 and Δt_2	More measurements, less accurate KPI, suitable for gaming apps
	More false positive IR detections	
	More true positive IR detections	

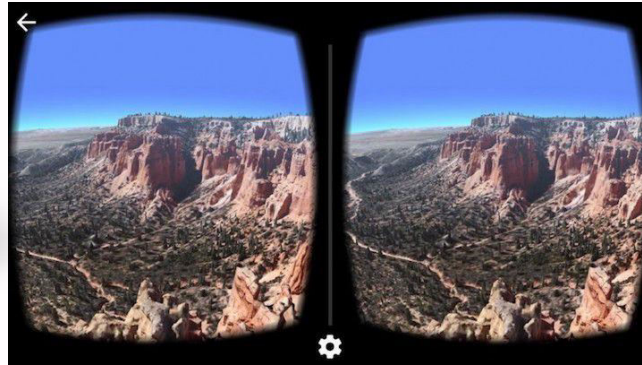
The IR matching score is another important trade-off parameter

KPIs Implemented

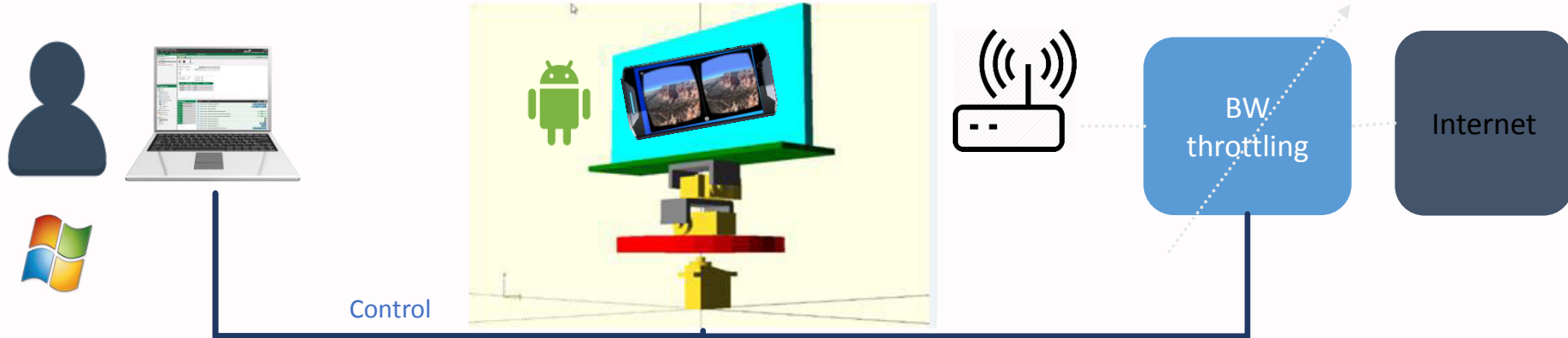
KPI	Definition
Network Resources Usage	Data Usage, Throughput
Device Resources Usage	Battery, CPU, GPU
Time to load the virtual world	Time elapsed from selecting a scenario (world, experience, etc.) to loading the 3D visual context
Immersion Cut-off	Probability that successfully started immersion is ended by a cause other than the intentional termination by the user
Lagging	Time elapsed from acting on the device to the reaction of the UI

Showcase: Testing Google Cardboard App

- VR experience, e.g., for Google Earth
- Replacing the mouse by the head movement

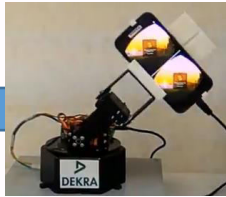
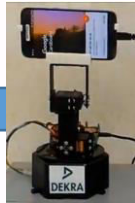


Showcase: Testing Google Cardboard App



Automatic test cycles: 40 repetitions / BW configuration

Showcase: Testing Google Cardboard App



Open App

Navigate through the app until click “start experience”

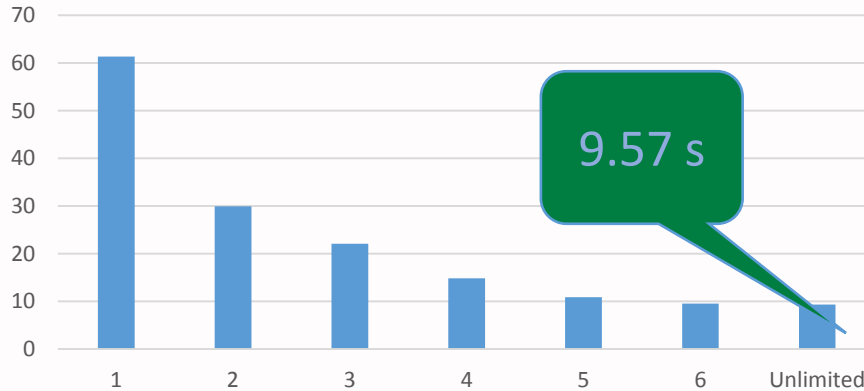
Measurement



Automatic test cycles: 40 repetitions / BW configuration

Showcase: Testing Google Cardboard App

KPI: Average Time To Load Scenario (s)



X-Axis: Imposed BW (Mbit/s)

KPI: Time to load scene

9.57 s (best scenario)

KPI: Network Data Usage

8 MB (all scenarios)

Showcase: Testing a Cloud Gaming app

- Test script:
 - Open App, Select game
 - Start game
 - Leave the car until it crashes with the first roadblock in its way (this happens after 280 seconds approximately)
 - Close game



We have selected this use case for repeatability across different network conditions

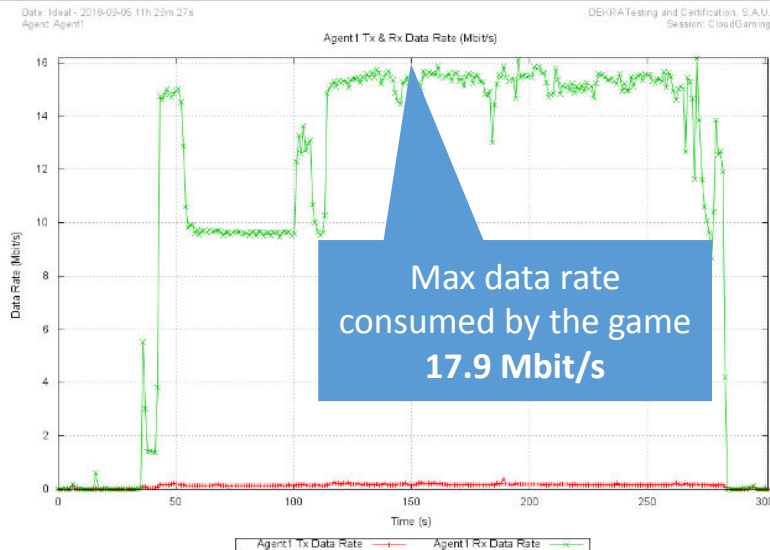
Showcase: Testing a Cloud Gaming app

Baseline Network Condition

RTT*	17 ms
DL Speed	90 Mbit/s
UL Speed	75 Mbit/s

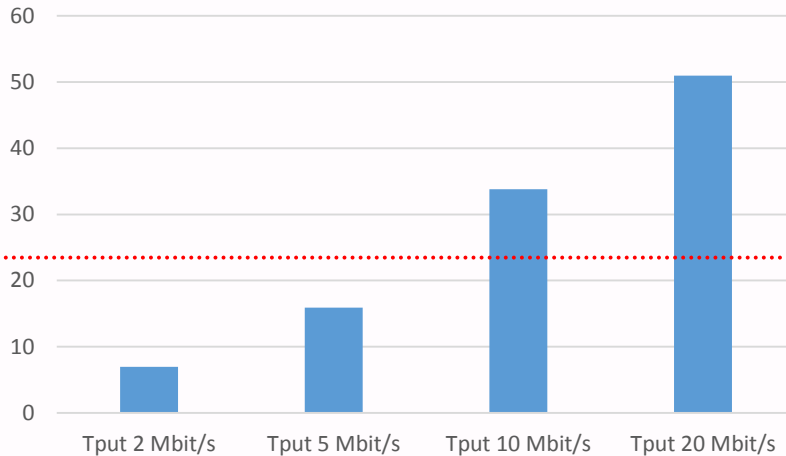
Baseline Frame Rate (fps)

Min	38
Avg	51.1
Max	55

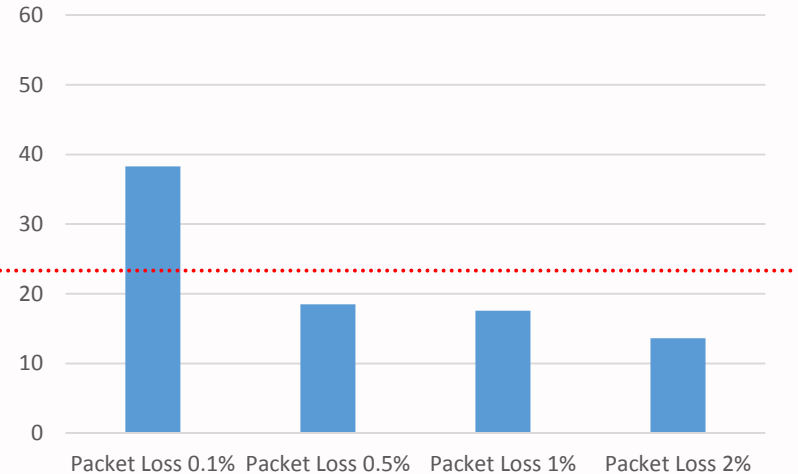


Showcase: Testing a Cloud Gaming app

Avg. Frame Rate (fps)



Avg. Frame Rate (fps)



Key-takeaways

- The “time to load scenario” KPI is severely impacted by the quality of the network access, mainly the available bandwidth (Mbit/s).
 - Online Virtual Reality apps consumes huge amount of network data, which has impact on network planning and deployments.
 - Online Virtual Reality apps requires high device GPU performance, so need flag-ship device for a good User Experience.
- 4G mobile networks are not suitable for 5G cloud gaming use case because...
 - The frame rate at the user device is unacceptable with a link capacity below 10 Mbit/s, or with a link loss (at IP level) above 0.1 %
 - The frame rate and the lagging at the user device is severely affected by fluctuations in the round trip time of the network (a.k.a. jitter).

Lesson-learnt

- Objective performance measurements provide insights about 5G VR and Gaming use cases.
- Thanks to the fast closed-loop response time of the solution on Android, the solution can be also used to measure online games apps.
- The image recognition library matching score parameter has impact on the accuracy of the “time to load scenario” measurement.
- The testing solution needs another upgrade to automate a gamepad. Online games may use external gamepad (instead of gyroscope/accelerometer) for which the implemented robotic platform is not suitable.

This testing solution has been developed inside the scope of TRIANGLE project



TRIANGLE Project

5G Applications and Devices Benchmarking

Co-funded by the Horizon 2020
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