ALL4TEC

Using Model-Based Testing during the life cycle of your product

Alexis DESPEYROUX & René-Christian TUYISHIME
Support And Pre-Sales

SUMMARY

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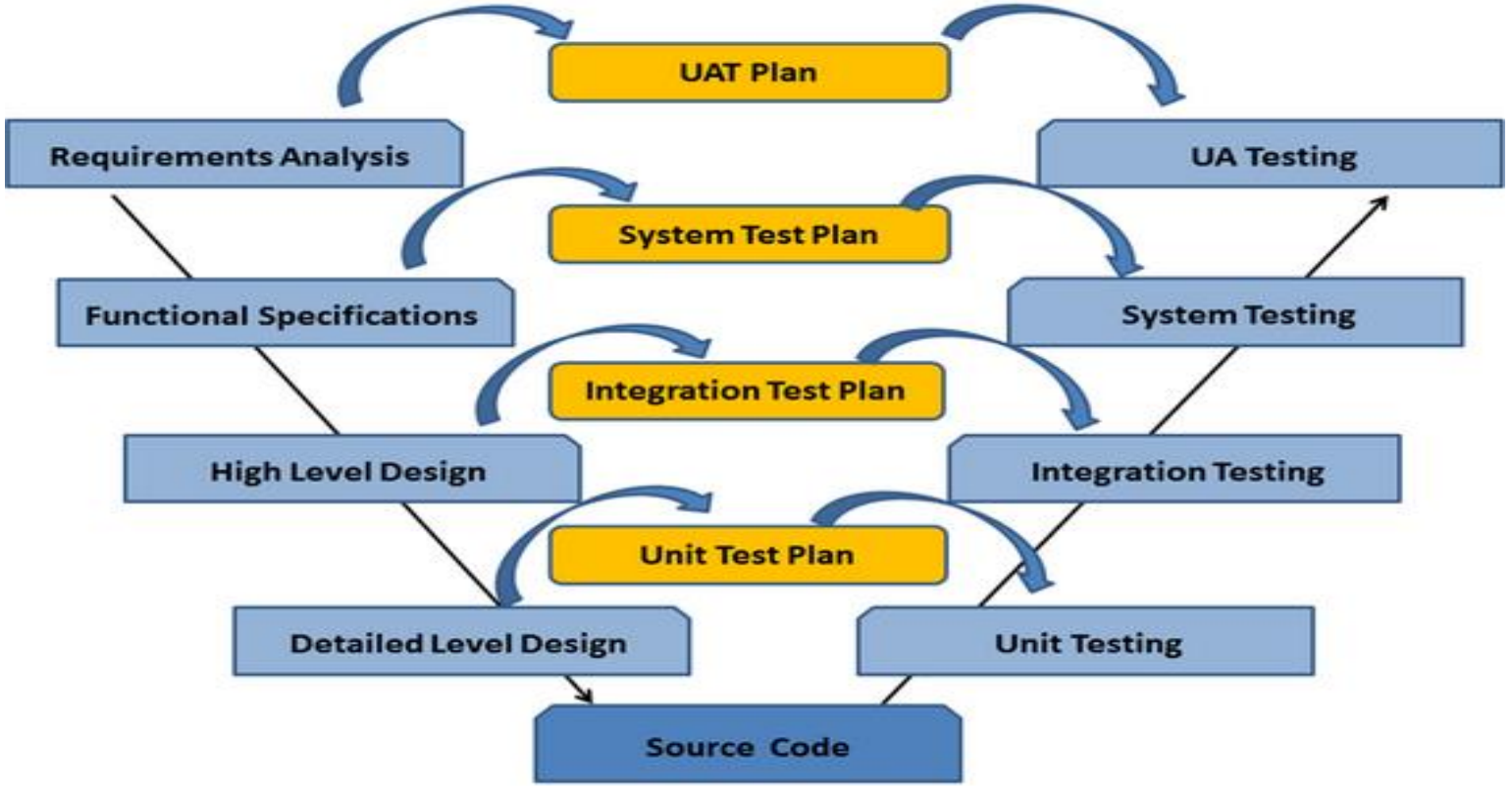
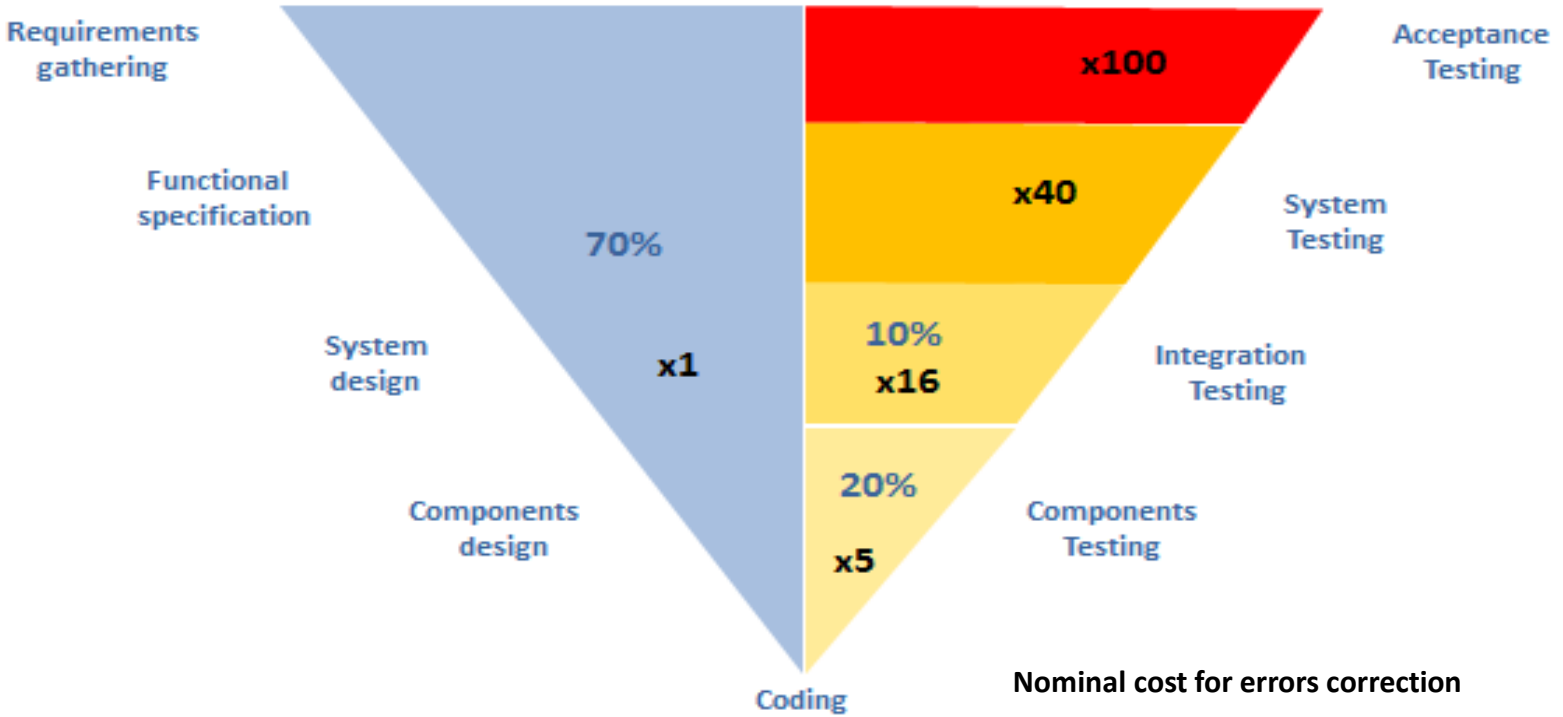
- **Introduction**
- Tutorial
- Conclusion

Test in V cycle



Test challenges

Error correction cost



Nominal cost for errors correction

- IBM Systems Sciences Institute
- Crosstalk, the Journal of Defense Software Engineering

Where errors are introduced

Some Testing issues

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- Test plans are written very later
  - ⇨ Often after the system implementation
  - ⇨ Errors detected later -> expensive correction
- Maintain test cases and test scripts
- Information on the requirements coverage rate
- Maintain resources
- Lack of communications between designers, developers and testers
  - ⇨ Lack of processes
  - ⇨ Projects are abandoned
- Etc.

Model-Driven Engineering

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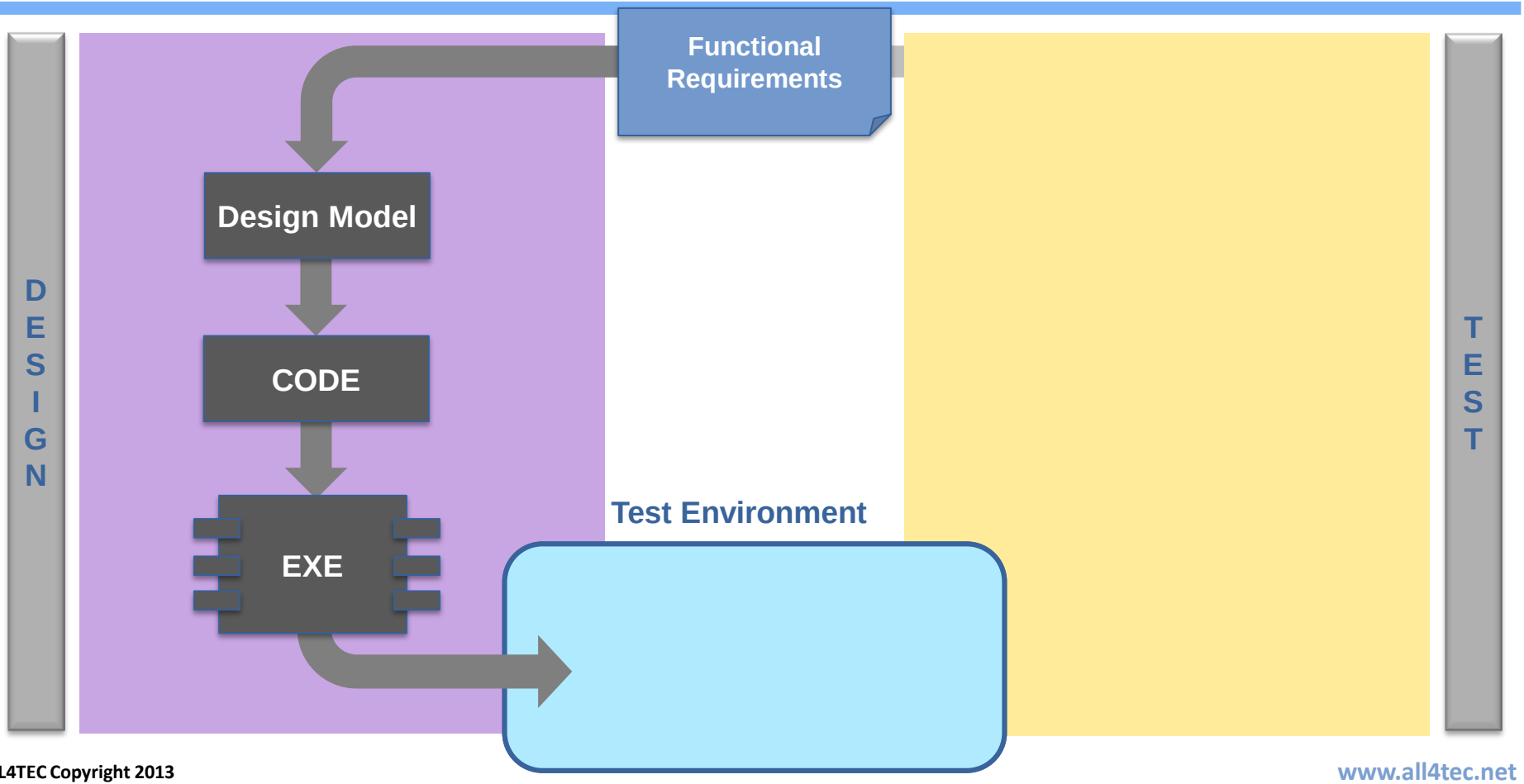

Design Model

- Embedded system development
- Abstract representation of the system based on specifications
  - ⇨ Verification
  - ⇨ Automatic code generation
  - ⇨ Executable in the target environment

Model-Driven Engineering

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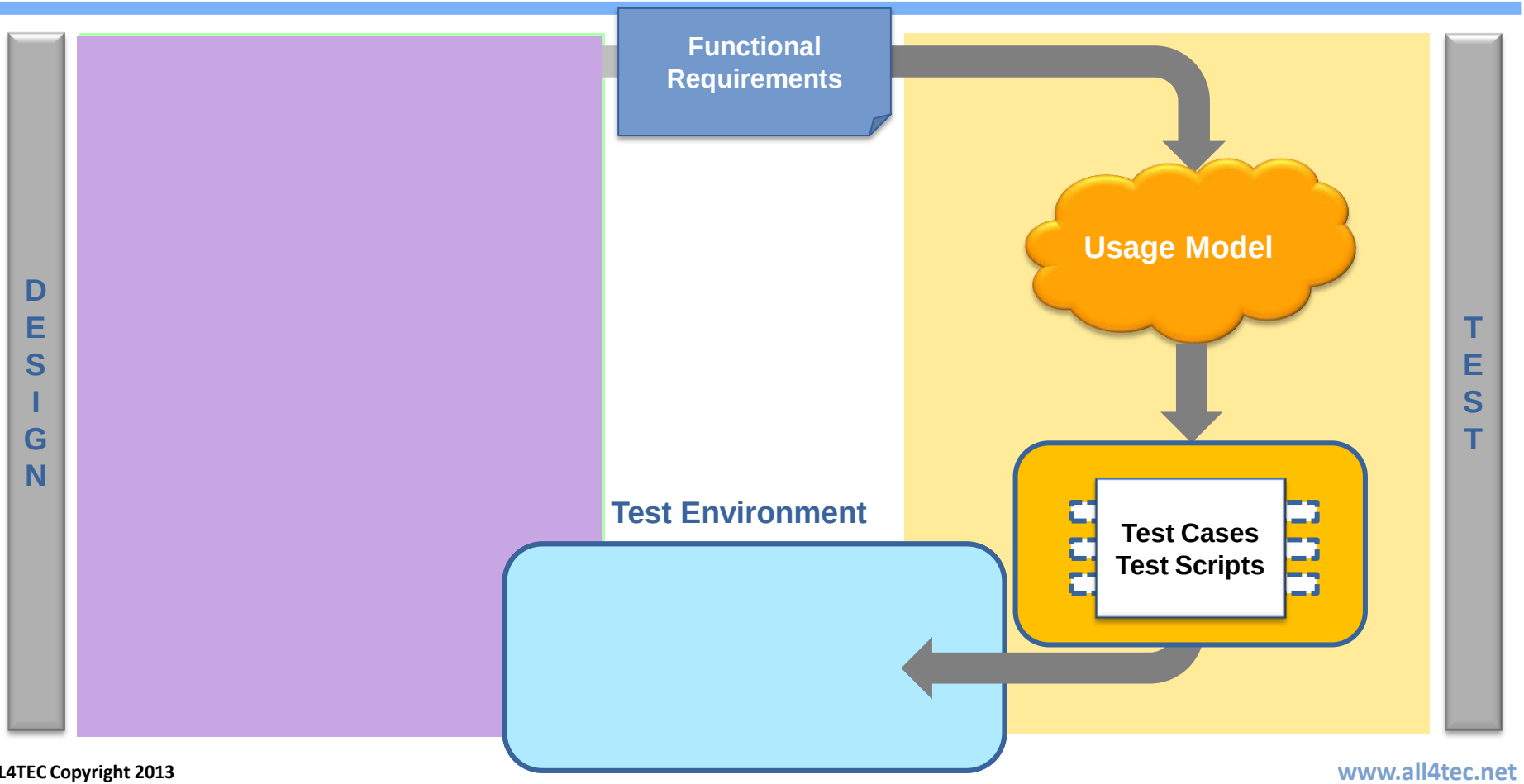

Usage Model

- Behavior of the SUT (System Under Test)
  - ⇨ Stimulations or actions
  - ⇨ Verifications
  - ⇨ Constraints (time,…)
- Formal languages are used
  - ⇨ UML, Markov chains, states charts…
- Test cases generation
  - ⇨ Test strategies
- The usage model construction has to begin as soon as we have a big part of requirements
  - ⇨ Detect and remove ambiguities early

Model-Driven Engineering

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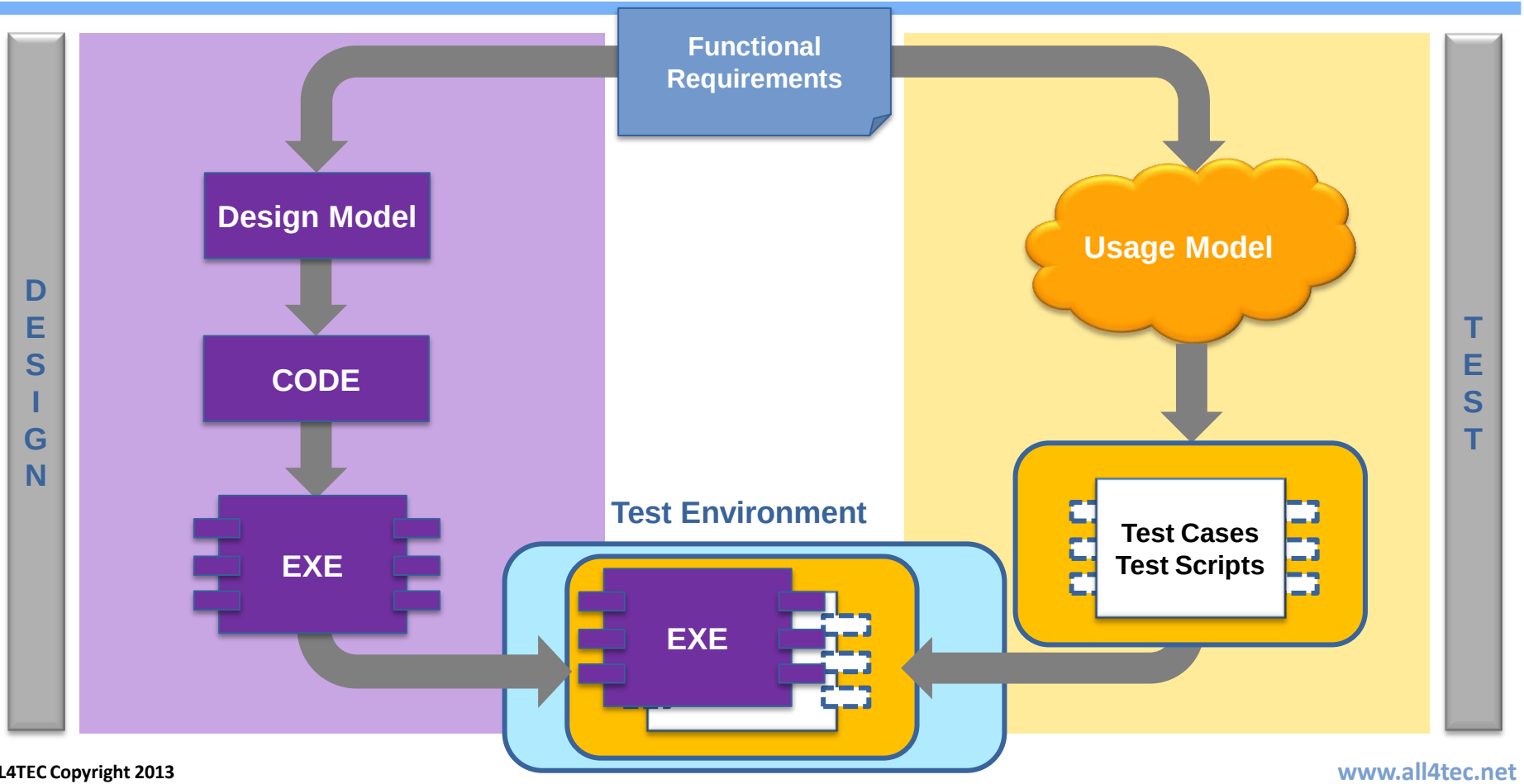
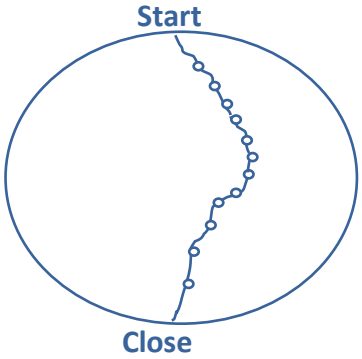


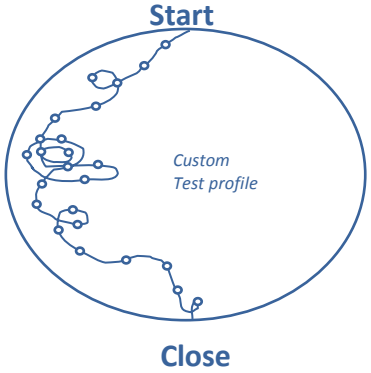
Test Strategies

Most probable approach



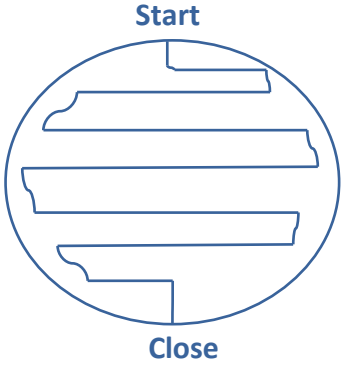
FREQUENCY
FOCUS

Risk based Approach User Oriented - Limit



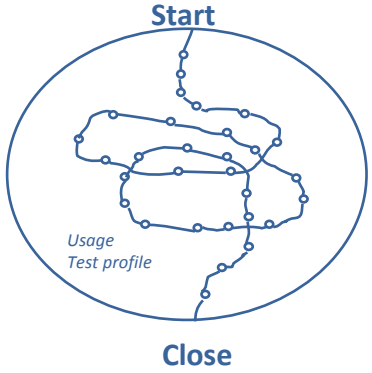
CRITICALITY, COMPLEXITY
UPDATE FOCUS

Arcs coverage approach



REQUIREMENTS
COVERAGE

Usage approach Random

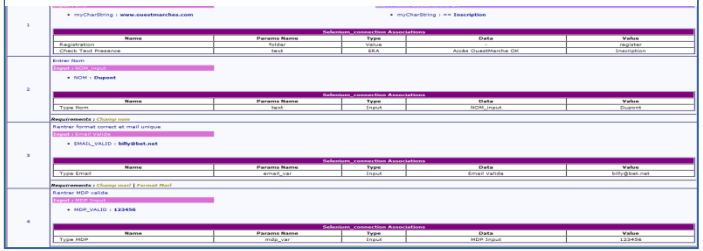


OPERATIONAL
COVERAGE

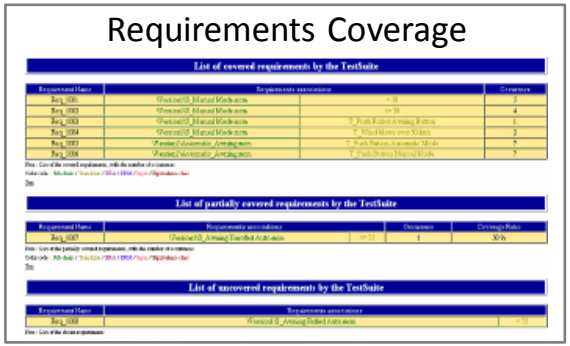
Test Cases

- **Manual test cases**
  - ⇨ Test suite
  - ⇨ Test generation report
  - ⇨ Requirement coverage reports
- **Translation in test scripts**
  - ⇨ According to test automation tool
- **Executed in a Test environment**

Test generation report



Requirements Coverage



SUMMARY

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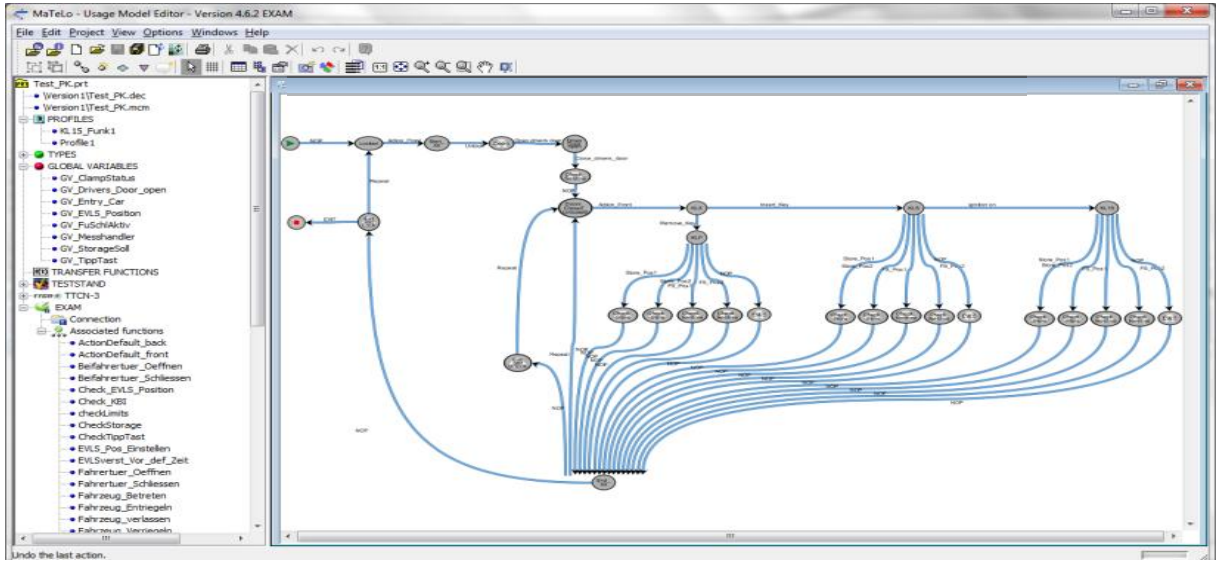
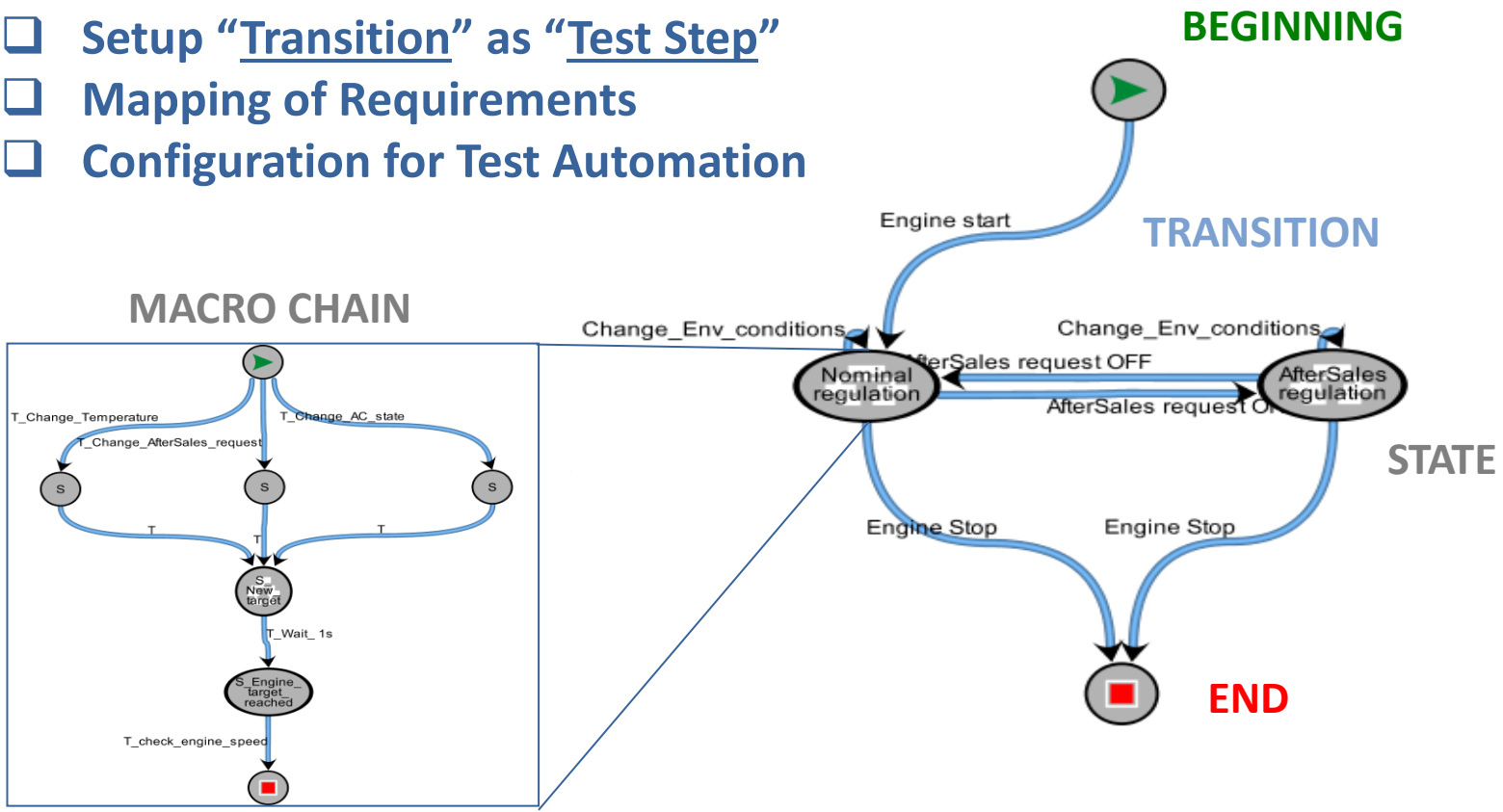
Used tools

- **MaTeLo (Markov Test Logic)**
  - ⇨ **Model-Based Testing approach**
  - ⇨ **Markov chains logic**

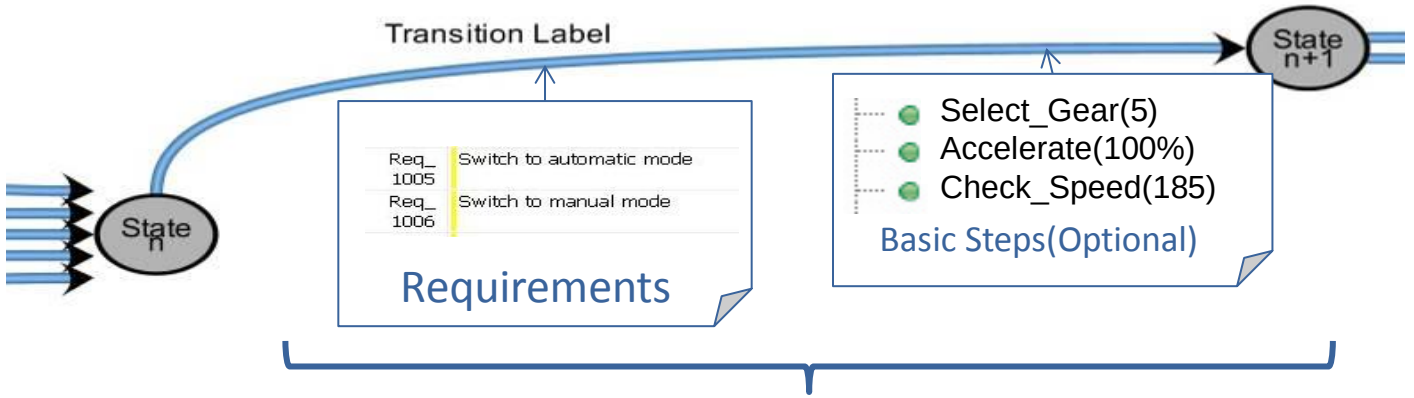


MaTeLo Usage Models

- Setup "Transition" as "Test Step"
- Mapping of Requirements
- Configuration for Test Automation



Model Transition = Test Step



Stimulations

Inputs Stimulation

- Equivalence Classes
- Timing

Transfer Function

python™

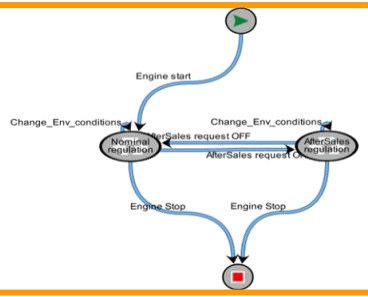
Scilab

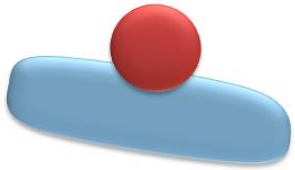
MATLAB SIMULINK

Verifications Points

- Expected Results
- Timing

MaTeLo Ecosystem





MaTeLo

Test Cases

Native		Plugin
Bench language	Scripting	
TESTSTAND	Python	VeriStand
EXAM	Selenium IDE	JUNIT
TTCN-3	Custom Script	Selenium
…	Open to ALL languages	…

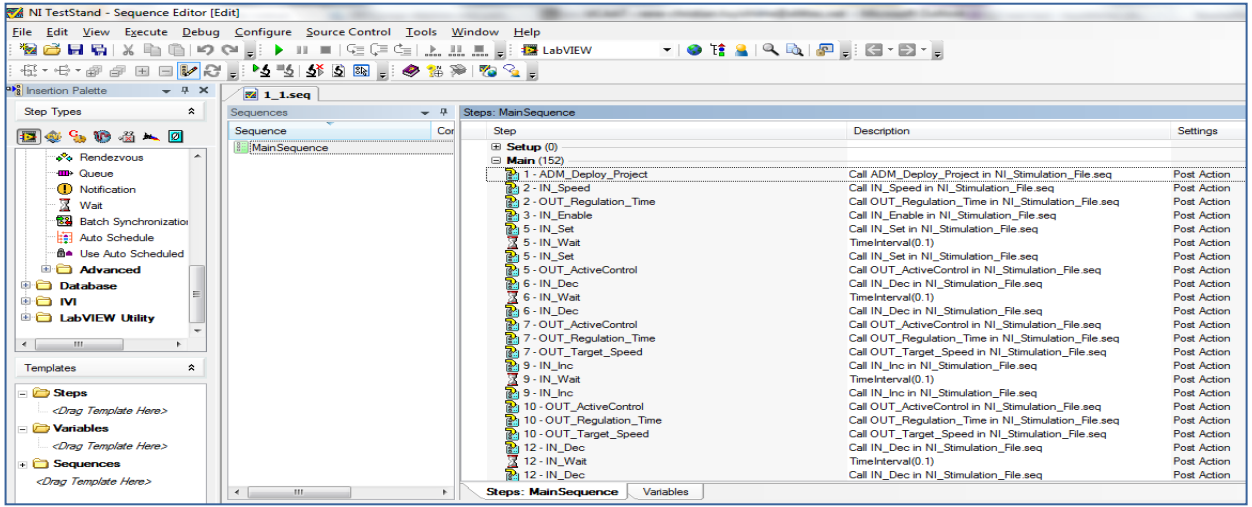
Test Scripts

Used tools

❑ NI TestStand

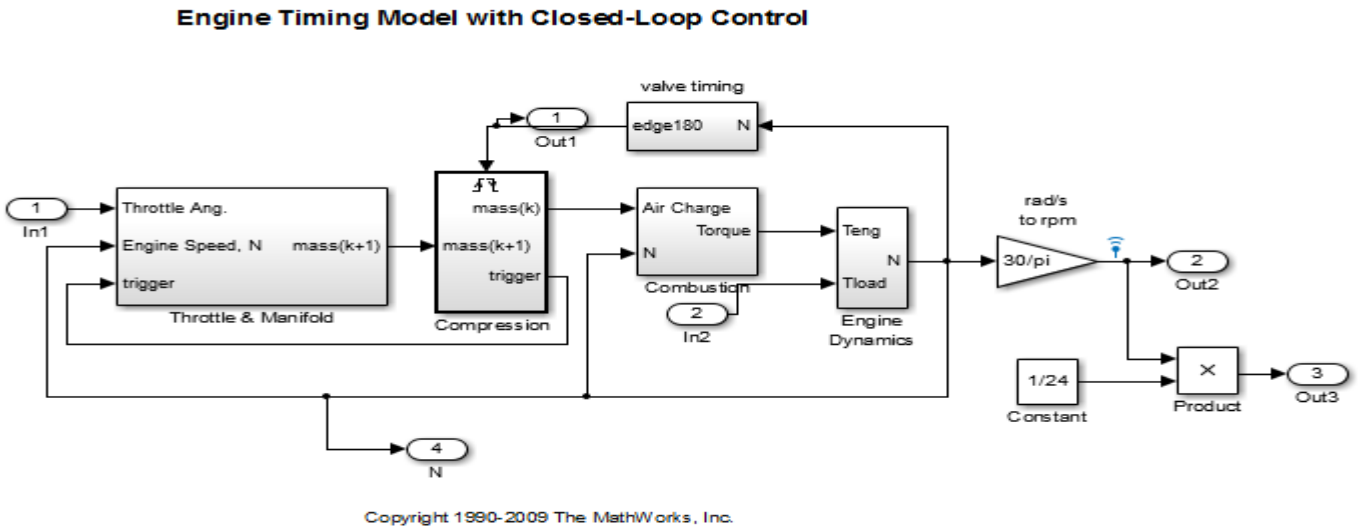
⇨ Test sequencer

- Execute test sequences generated by MaTeLo

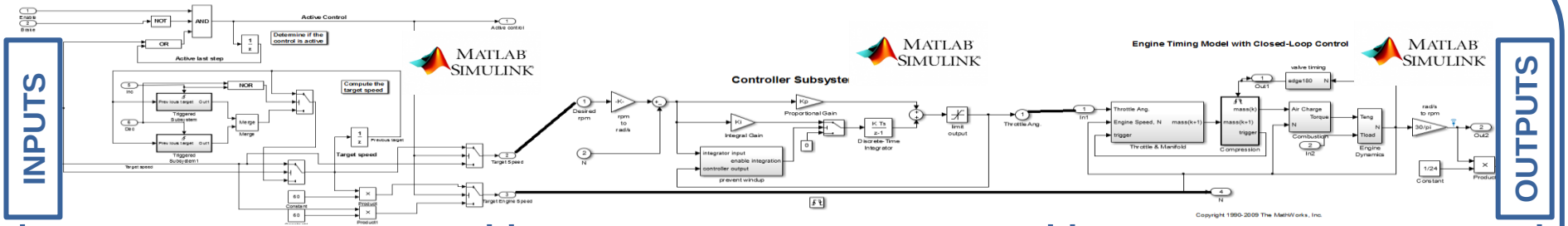


Used tools

❑ Matlab Simulink for design models



SUT: Cruise Control Simulation



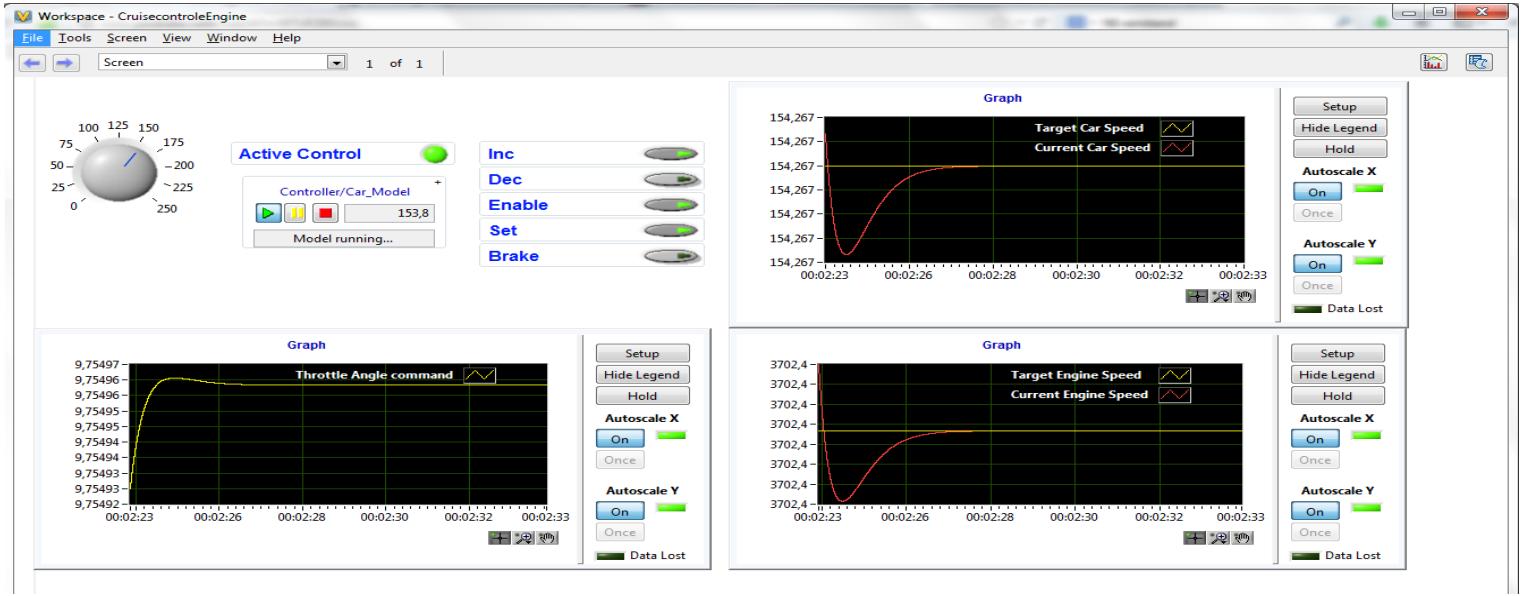
Control command | Car Model | Cruise Controller

NI VeriStand

Used tools

❑ NI VeriStand

⇨ Real time environment



Testing methodology

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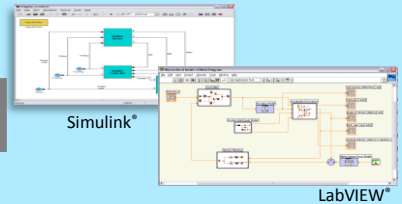
NI VeriStand

Implement

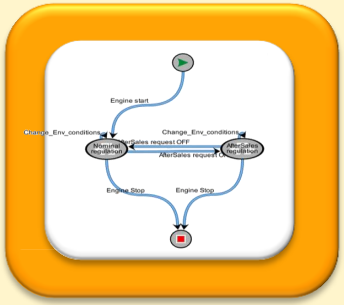
System Models



Functional Requirements

Scenarize

MaTeLo



Generate

Test Cases

Translate

Test Stand Test Script

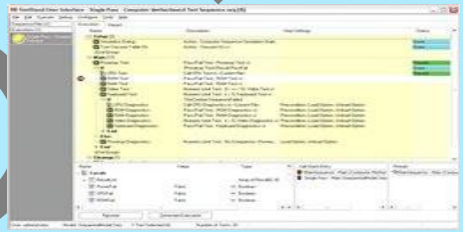
Import

Add

Real-Time Testing and Simulation Software

NI VeriStand

Run



NI TestStand

SUT requirements

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Req_01:

- A push on the ON button activates the cruise control and the led is switched on

Req_02:

- A push on the OFF button deactivates the cruise control and the led is switched off

Req_03:

- Pressing the brake pedal deactivates the cruise control and the led is switched off

Req_04:

- **When the cruise control is activated:**
- A push on the button SET imposes the current speed as the target speed
- One push on the button “Inc” increases the cruise control target speed by 1km
- One push on the button “Dec” decreases the cruise control target speed by 1 km
- The increase or decrease of 1km must last at maximum 50 ms

Req_05:

- The cruise control is effective between [30,150] Km/h

SUMMARY

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Live DEMO

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- **Conclusion**

Conclusion

- Quantified and optimized requirements coverage
  - ⇨ Model-Based Testing tools give requirements coverage indicators
- Consolidation of functional requirements
  - ⇨ Ambiguities in specifications are removed early
- Pertinent test cases (usage profiles, risks, …)
  - ⇨ Possibility to define usage profiles
  - ⇨ Risks are taken into account in the generation strategies
- Easy test cases maintenance
  - ⇨ It is more easier to maintain an usage model than manual test cases
- Easy test cases automation
  - ⇨ Test effort lowered

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ALL4TEC Laval (HQ)	FRANCE
ALL4TEC Paris	FRANCE
ALL4TEC Munich	GERMANY
ALL4TEC Stockholm	SWEDEN

Sales	**sales@all4tec.net**
Support	**http://all4tec-support.net**
Marketing	**marketing@all4tec.net**

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